



Transdisciplinary Approaches in Robotics for Social Innovation: Addressing Climate Change, Workforce Displacement, and Resilience in the Age of Disruption

Parankush Koul

Department of Mechanical and Aerospace Engineering, Illinois Institute of Technology, 3201 South State Street, Chicago, 60616, Illinois, United States of America

Received 9 October, 2024; Revised 30 December, 2024; Accepted 1 January, 2025

Available online 1 January, 2025 at www.atlas-tjes.org, doi: 10.22545/2025/00269

Abstract: *In this review paper, we consider transdisciplinary approaches to robotics and how they can be applied to promote social innovation to solve pressing problems such as climate change, workforce displacement, and resilience in times of disruption. It demands the establishment of cooperative models to bridge the technological gap between social realities and fairer, sustainable futures. Businesses such as SkyGrow, which makes automated tree-planting robots for targeted reforestation, show the promise of such technologies. The paper highlights the need for assessments to understand community needs and engage the community and industries involved to find possible use cases for robotics. It encourages participatory designs rooted in end-user insights, which will make the technologies being created reflect local demand. After all, it takes a collective for effectively navigating the complexities of today's problems in robotics and social innovation.*

Keywords: Transdisciplinary, Social Innovation, Robotics, Climate Change, Workforce Displacement.

1 Introduction

Robotics and social innovation offer special opportunities to solve urgent global problems such as climate change, job loss, and the stability required in a disrupted world. The technology of robots is in a continuous transformation, which makes it possible to design and implement systems that not only boost productivity but also solve complicated social challenges (Seibt et al., 2020). When the world faces climate change, for example, emerging robotics can allow sustainability solutions, such as precision agriculture and waste management, both essential to reducing carbon emissions and environmental management (Cai et al., 2019). Furthermore, the rise of automation and intelligent systems has raised issues of workers' mobility and requires a transdisciplinary solution that is at once a hybrid between technological change and social-economic effects on communities (Rasmussen et al., 2007). With a cross-fertilization across the social sciences, engineering, and policy realms, a holistic picture of such dynamics can be cultivated, and creative interventions to reduce the bad while reaping the greatest benefit for society (Pramjeeth et al., 2022).

Resilience, in turn, is necessary to enable societies to cope and recover from climatic, economic, and technological disruption (Nambisan et al., 2020). There, robotics can help, both directly and indirectly through community participation and ownership, leading to sustainable practices and resiliency at the ground (Michalec et al., 2021). In this review paper, we seek to understand such cross-disciplinary robotics innovations and how they could be drivers of social innovation in tackling the combined problems of climate change, workforce migration, and resilience. Through detailed analyses of recent developments and case studies, it emphasizes the necessity for collaborative arrangements that bridge the divide between technology and society to deliver more equitable and sustainable futures. If robotics is placed into a larger discussion of social innovation, we can see that a whole approach is vital to solving today's challenges, which will help foster a more integrative and futuristic mindset in the discipline (Seibt et al., 2020; Nambisan et al., 2020).

2 Defining Transdisciplinarity in Robotics for Social Innovation

Transdisciplinarity reframes how we think about solving worldly problems by putting an emphasis on cross-disciplinary cooperation to integrate knowledge, experience, and practices from different disciplines. In the case of robotics for social innovation, this model plays a central role in solving multiple problems, such as climate change, displacement, and resilience in disruption. Essentially, transdisciplinarity aims to bring technology and social realities in line with one another through cooperation between universities, industry, and the public. As explained by Leiria and Martins' report on climate change in Portugal, this approach draws from psychology, technology, economics, and politics to devise integrated plans tailored to the entanglement of social and ecological systems (Leiria & Martins, 2022). In a similar spirit, Moñivas stresses a multi-level perspective of resilience that encompasses biology, culture, and the environment in a way that deepens the notion of dynamic human-environment interaction (Moñivas, 2022). In robotics, transdisciplinary approaches mean that the solution meets societal needs and interests. Participatory design and community, in the words of Williams et al. in public health, create local control of innovations and be inclusive (Williams et al., 2016). Such methods are consistent with Lawrence's embrace of culture and society to solve problems worldwide, such as poverty and climate change, through cross-disciplinary collaboration based on human agency (Lawrence, 2022).

One of the key characteristics of transdisciplinarity in robotics is that it bridges the gap between the technical and the ethical (as Herrera-Vega notes when she discusses AI's impact on climate governance). In connecting science and the law, it creates accountability and moral responsibility while solving techno-social issues (Herrera-Vega, 2022). And likewise, del Cerro Santamaria sees robotics teaching as transdisciplinary, bringing together engineering, social sciences, and community expertise in order to create solutions that can benefit society (Santamaria, 2015).

In this article, the transdisciplinary approach applies cross-disciplinary cooperation, participatory design, and collaborative communication networks to tackle pressing issues in socially sustainable ways. This mirrors Gehlert et al.'s approach to creating synergy and creative solutions with high-level team engagement and stakeholder engagement (Gehlert et al., 2015). In doing so, it not only solves technical issues but also aligns robotic technologies with societal needs for sustainability, fairness, and resilience.

By means of these transdisciplinary conceptualizations, this research contributes to the construction of novel, humane, and transformative robotic technologies—generating social innovation in the age of change.

3 Methodologies for Implementing Robotics for Social Innovation

The application of robotics for social innovation, particularly in climate change, displacement, and resilience in disruptive times, requires coherence. It is possible to develop and implement such robotic systems using a number of approaches.

3.1 Needs Assessment and Stakeholder Engagement

The needs analysis is essential to determining which issues communities specifically have to grapple with as they relate to climate change and employment. Involving local communities, environmental groups, and industries helps identify the right robotics applications. Active design frameworks can help speed this up by including end users' feedback in the development of robotic technologies (Capasso, 2023). Furthermore, with the use of stakeholder theory, the voices of all stakeholders are considered, and the solutions are more compatible and productive (Pichot et al., 2021).

3.2 Technological Development and Prototyping

Once those requirements have been defined, the following relates to developing the necessary robotics. Agile development tools support iterative robot prototyping and testing in practice. This method enables quick adaptations as per user needs and the demands of the environment. For instance, robots range from driverless cars for mobility to drones for the observation of the environment (Social Sector Network, 2024). A focus on design can help ensure that the technologies that are being created meet both ethical requirements and user expectations. The Pepper robot is a social robot example that has been shown to provide user interaction and happiness through its embodiment (movement, gesture, and conversation) as seen in Figure 1.

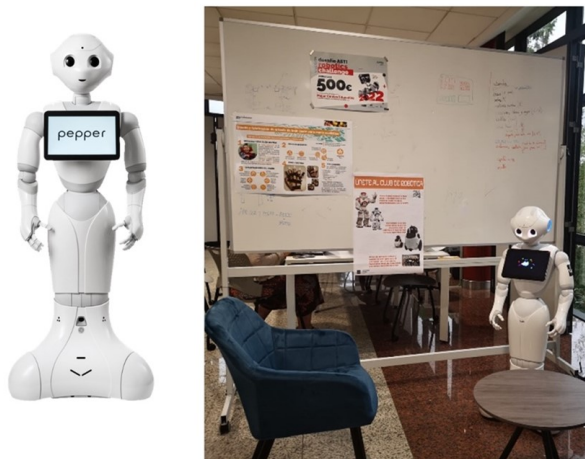


Figure 1: The Pepper robot and the environment of the experiment (Corrales-Paredes et al., 2023).

3.3 Pilot Projects and Scaling

Pilot projects are necessary to prove the proposed robotic solutions before they are put on the market. These projects could be deployed to collect data on how the technology solves the identified problems. Robotic solutions in renewable energy plants, for example, can streamline maintenance activities and thus increase efficiencies and lower CO₂ emissions (Dickson, 2023). Once validated, a strategy for deploying the technology on a large scale will include collaborating with the market and the government to encourage mass adoption and integration into existing systems (Advanced Robotics for Manufacturing Institute, 2024).

3.4 Monitoring and Evaluation

The creation of a monitoring and evaluation mechanism is essential for calculating the effect of robotics on social innovation results. This model should be geared toward quantitative and qualitative indicators

like stakeholder satisfaction, ecological benefits, and economic consequences of workforce loss. Repetitive feedback loops can allow robotics systems to continuously improve in response to changing environmental and social environments.

3.5 Policy Advocacy and Ethical Considerations

We need policy-enabling measures for using robotics responsibly to solve social problems. It is important to talk with policymakers about policies that allow robotics to be incorporated into labor markets and environmental programs (Pasquale, 2021). Furthermore, data privacy, job loss, and autonomy have to be dealt with ethically if the public is to trust and allow robotics (Etemad-Sajadi, 2022). By integrating ethics into design and deployment, robots work for the public good and not against it.

4 Robotics in Addressing Climate Change

4.1 Environmental Monitoring and Data Collection

Robotics dramatically increases the efficiency and precision of environmental monitoring and data acquisition. Robotic mobile bots and aerial drones, for instance, are becoming much more common tools for high-resolution air and water quality measurements. This is an essential feature in measuring pollution and making sense of ecological changes in real time. Further, drones that include environmental DNA (eDNA) sampling sensors can keep a close eye on biodiversity by harvesting genes from hard-to-reach locations like canopy trees (Aucone et al., 2023). Such robots can also autonomously move to different locations and provide coverage of wide-ranging environmental zones with a tremendous increase in data quality and spatial resolution (Lan et al., 2024).

Robotics can also assist in the adaptive planning of data collection, a solution for data collection over a wide variety of terrain (Hitz et al., 2017). For example, some high-tech flying robots include perching systems to save energy but still be ready to gather information indefinitely without flying (Lan et al., 2024). Using these types of robotic systems has been found to result in more energy savings and greater functionality, making them an increasingly valuable tool in the fight against the environment.

4.2 Disaster Management and Emergency Response

Robotics helps disaster response by facilitating fast assessment and data gathering. For example, autonomous underwater robot vehicles are able to rapidly gather information from contaminated waters, which can be used to assess natural hazards or human activities as they occur (Laut et al., 2016). With the use of self-guided systems, rescuers will be able to access valuable data about the locations of casualties without humans' lives and make informed decisions in crisis situations.

Also, robots like quadrupeds have been developed to help travel through urban environments to monitor air quality, which is extremely valuable in real time to disaster responders (Hansen et al., 2024). Diverse sensors enable these robots to sense the environment accurately and thus enhance the overall security and efficiency of emergency services.

4.3 Sustainable Development and Conservation Efforts

Robotics also plays a central role in sustainable development and conservation. Robotic agricultural robots can maximize crop yield by sensing health conditions, thus minimizing resource wastage (Domdouzis, 2021). These robots can support sustainable farming and thus boost production and reduce the environmental footprint of farming.

Further, robotic systems can be applied to conservation to keep track of threatened species and habitats. Sensor-enabled and imaging robots help scientists collect data on wildlife populations and environmental trends, which they can then use to plan for conservation action (Nkwazema et al., 2021). Automation of

data gathering allows robotics to de-stress monitoring, freeing conservationists to allocate resources to strategy and execution.

5 Transforming the Workforce with Robotics

Automated work, job loss, new skill demand, and the creation of inclusive employment are all facets of integrating robotics in the workforce. Everyone is important to the future of work as technology develops.

5.1 Automation and Job Displacement

While robots and automation are changing industries with productivity and efficiency improvements, they're also leaving jobs. Automating mundane and hazardous tasks creates productivity increases in manufacturing, logistics, and service sectors (McManus, 2023; Santhosh et al., 2023). Although robotics will take away some jobs, it will create new ones for individuals who are prepared for it (Santhosh et al., 2023; Adhikari, 2024). These technologies are especially visible in manual work and the data processing industry, where repetitive work is getting automated by robots (Santhosh et al., 2023; Raj et al., 2024).

Further, we know from the past that automation leads to a loss of jobs in the low-skilled labor force, a socioeconomic concern, particularly for the role of policies to aid displaced laborers (Karangutkar, 2023; Nnamdi et al., 2023). This makes proactive measures by institutions and governments essential to counter the negative impact of job automation through retraining and reskilling programs (Karangutkar, 2023; Mahajan et al., 2023).

5.2 Skills for the Future: Reskilling and Upskilling Initiatives

The ebbing job market requires reskilling and upskilling efforts to equip workers for the future. With automation taking over job responsibilities, the market for digitally literate, critical thinkers, and pragmatists is on the rise (Santhosh et al., 2023; Alcover et al., 2021). Reskilling programs retrain employees with skills related to new technologies and the changing industry, thereby making them more mobile (Raj et al., 2024).

Most companies have training and educational schemes for employees to learn how to master skills like robotics, artificial intelligence, and data science. The return on this investment in human capital doesn't just assist displaced workers to adjust; it improves organizational efficiency (Oladele et al., 2024; Mahendran, 2024). Moreover, industrial and academic collaborations are the key to predicting the demand of skills in the future and keeping up with the curriculum (Santhosh et al., 2023; Gangoda et al., 2023). This makes continuous learning a must to keep up with today's fast-moving technological workforce.

5.3 Creating Inclusive Job Opportunities with Robotics

However, robotics can provide inclusive employment despite displacement. Robotics innovations can create industries and jobs with novel skill sets (Adhikari, 2024; Adebayo et al., 2024). These changes matter, in particular for marginalized groups, such as women and underrepresented minorities, who can reap benefits of targeted interventions that support technology access and skills training (Nnamdi et al., 2023; Paudel, 2024).

Additionally, robotics in the right mix can also improve workplace safety and create jobs involving human-robot cooperation, where humans would be required to oversee and control automated activities (Mahajan et al., 2023). Diversity could be further increased by having policies that promote diverse hiring practices and encourage people of diverse backgrounds to enter the tech industry (Oladele et al., 2024; Gangoda et al., 2023). As long as access to training and employment is fair, the workforce will be a more diverse and adaptable group that can survive in an automated future (McManus, 2023; Mahendran, 2024).

6 Enhancing Social Resilience through Robotics

The topic of social resilience through robotics is multidimensional, with elements ranging from local care and health to intercultural communication. These themes show how robotics can become a basis for building resilience in societies with diverse issues.

6.1 Community Resilience and Support Systems

Robotics can play a significant role in increasing community resilience through better support systems. Community resilience is a measure of a community's resilience against and recovery from negative events like economic decline, natural disasters, or civil strife. Automated community support systems can enable better responses to these problems. The deployment of robots in neighborhood gardens, for example, has demonstrated that such interventions support social networks, collective identity, and knowledge sharing among neighbors (Taylor et al., 2022). Then there is robotics' potential to generate formal support, especially state services and NGOs, which can prove critical during crisis conditions (Bandile, 2024). Technology will also enable communities to become better able to handle emergencies and form more resilient social networks.

6.2 Public Health and Safety

The health and safety effects of robotics cannot be understated, particularly during times of crisis. In the medical domain, new research highlights the potential of robots in emergency situations, which can also help in better providing health services. For instance, during the COVID-19 pandemic, hospitals had already started to use robots to disinfect and administer medicines, minimizing human interaction and risk of transmission (Darmadi et al., 2023). In addition, robotic assistants can be applied to public health information to enhance crisis management through the identification of links between health outcomes and demographic variables (Ebbrecht & Chen, 2023). In this way, robotics contributes to not only healthier lives but also to increased public confidence by ensuring people and societies' safety during medical emergencies.

6.3 Cross-Cultural Collaboration in Robotics

Collaboration across cultures is a key ingredient for robotizing social resilience. Robotic innovations could be tailored to specific issues and conditions in other communities by connecting with cultures and communities of other countries. Collective actions can result in exchanging best practices and the creation of technologies adapted to particular social conditions (Hess, 2020). Moreover, government agencies and non-governmental organizations can establish environments to support multicultural robotics projects, using a variety of insights and skills to solve common social issues. Through this holistic approach, robotics is not just developed in a technically advanced but socially appropriate way, which allows societies to improve resilience as a whole (Agarwala et al., 2022).

7 Transdisciplinary Framework for Robotic Innovation

The adoption of a transdisciplinary robotics approach to social innovation must tackle world-critical challenges, including climate change, workforce displacement, and resilience in the age of disruption. Not only does this bring together expertise from different disciplines, but it also promotes collaborative work to find effective solutions.

7.1 Understanding Transdisciplinary Framework

The transdisciplinary approach emphasizes multidisciplinary collaboration and unification of sources of knowledge for the purpose of addressing interconnected social problems. Such a framework incorporates the

stakeholders of academia, industry, and policy so that the process of knowledge production is cross-sectoral and serves practical challenges (Dennison, 2017). It seeks to produce new and sustainable, and also acceptable, solutions, crucial for resolving global challenges such as climate change and labor migration.

7.2 Steps for Implementation

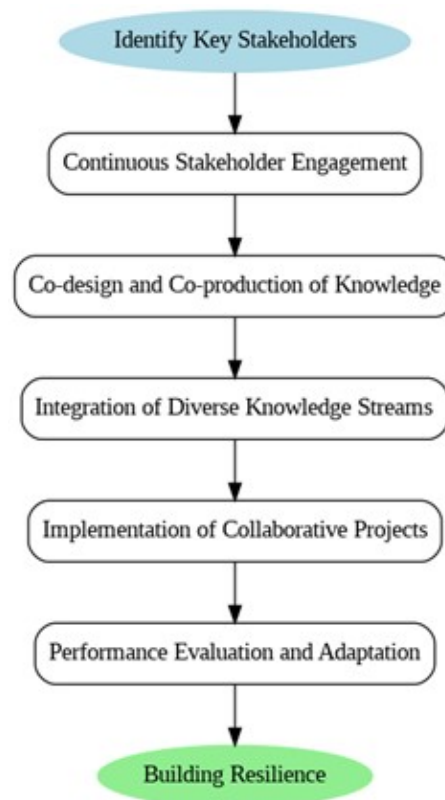


Figure 2: Steps to Implement the Transdisciplinary Framework.

- *Identify Key Stakeholders:* Firstly, list stakeholders who are in both the robotics and social innovation industries. These can be engineers, scientists, policymakers, and members of the public. Working with stakeholders from the very beginning ensures that everyone has an opportunity to participate and that there is full transparency about the problem. This is the critical role that develops trust and commitment to collaborative work (Höpfel et al., 2023).
- *Continuous Stakeholder Engagement:* Creating ongoing stakeholder conversations is the key to tapping into stakeholders' needs and opinions. This can be done through workshops, focus groups, and conversations where ideas and knowledge can flow. Regular communication allows stakeholders to define the goals and interests for the project as a common vision.
- *Co-design and Co-production of Knowledge:* The transdisciplinary method requires co-design involving stakeholders who jointly work on the research agenda, methodology, and intervention. Such participation increases the utility of the research and enables its base in actual conditions, leading to better chances of success (Dennison, 2017).
- *Integration of Diverse Knowledge Streams:* An important aspect of the framework is the integration of different knowledge layers. This means combining the knowledge of social sciences, robotics,

environmental science, and policy research into comprehensive solutions to climate change and labor shortages (Blaurock et al., 2022).

- *Implementation of Collaborative Projects:* Once stakeholders have agreed on a vision and brought in their collective knowledge, they can launch joint projects around specific issues. Robotics, for example, can be used in environmental monitoring or renewable energy generation, in which technology contributes to limiting climate change (Chen, 2023). Such projects should also consider the impacts of labor displacement, involving affected communities in the transition process (National Governors Association, 2020).
- *Performance Evaluation and Adaptation:* By establishing metrics on how well the projects are going, stakeholders can measure results in a systematic way. The continuous feedback loops should be configured to change tactics depending on lessons learned. That's the process that helps refine strategies and keep them agile in light of changing environments.
- *Building Resilience:* The last thing to do is to create community resilience. This can mean training employees for the new roles brought about by robotics and automation (Li et al., 2023). Skills-based and adaptable training can help to counteract the negative impact of workforce migration while encouraging innovation and sustainability.

The adoption of a transdisciplinary robotics model for social innovation demands well-designed stakeholder engagement, co-design, knowledge sharing, project implementation, assessment, and resilience building. With these initiatives in mind, it is now possible to effectively tackle the nexus of climate change and migration, offering long-term solutions that will benefit society as a whole (Dennison, 2017; Blaurock et al., 2022).

By providing a shared, adaptive environment, such a framework can best address the challenges of today's societal reality so that robotic technologies can act as instruments of social reform.

8 Companies Utilizing Transdisciplinary Approaches in Robotics for Social Innovation

A number of companies are combining robotics with transdisciplinary solutions to address pressing global challenges like climate change, workforce exodus, and improving resilience in the age of disruption. Here are 10 of the companies that are leading these initiatives:

- *SkyGrow:* An Australian start-up whose mission is to develop self-propelled tree-planting robots to address climate change by planting trees more efficiently, thus solving land restoration and biodiversity loss (Worcester Polytechnic Institute, n.d.).
- *FarmWise:* Utilizes automatic ground robots for precision farming that can do tasks such as weeding and crop monitoring without chemical inputs, helping to create sustainable agriculture and environmental protection (Worcester Polytechnic Institute, n.d.).
- *Zipline:* Delivering medical supplies autonomously with drones, Zipline's goal is to provide access to healthcare by pursuing both technology and social responsibility in the face of logistics worker shortages (Khanna & Gonzalez, 2020; Baker, 2017).
- *UTS's Magic Lab:* A research lab at the University of Technology Sydney builds social robots for elderly care, robots capable of engaging with and providing care, bringing social needs and workforce issues to healthcare (University of Technology Sydney (UTS), 2023).
- *Outrider:* Manufacturer of autonomous electric yard trucks to mitigate carbon emissions of the freight yard operations and help support the larger mission of sustainable transportation as well as tackle labor issues in logistics (Worcester Polytechnic Institute, n.d.).

- *AES Corporation*: This energy conglomerate is the inventor of robotized solar farm construction systems that help to ensure efficiency in renewable energy installations as well as reducing shortage of labor by accelerating crucial installation steps (Chen, 2023).
- *Aerones*: This company offers tethered drones to maintain and inspect wind turbines, improving the efficiency of renewable energy systems and the high skill level of the energy workforce (Chen, 2023).
- *Unleash*: Adopts drone technology to boost efficiency and safety in maintenance of wind farms, thereby stepping into the gap of labor while driving renewable energy projects (Chen, 2023).
- *ZenRobotics*: Creates robotic waste sorting, recycling, and contamination reduction systems, which directly supports waste management in the age of growing environmental demands (Worcester Polytechnic Institute, n.d.).
- *Boston Dynamics*: Partners with various industries to provide cutting-edge robots to support any industry, from construction to logistics, allowing human employees to spend time on more valuable tasks and supporting workers' adaptation to technological advancements (Mapue, 2024).

9 Challenges and Opportunities

Transdisciplinary robotics for social innovation presents challenges as well as opportunities, especially as society struggles with looming problems of climate change, labor mobility, and resilience to disruption.

9.1 Challenges in Transdisciplinary Approaches

In robotics, one of the biggest issues with applying transdisciplinary methods is the very nature of cross-disciplinary collaboration. The fusion of ideas from social sciences, engineering, and environmental science involves negotiating cultural differences, terminology, and practices that are often not straightforward to fit together (Peruzzini et al., 2020). It's further complicated by technology's rapid transformation and the difficulty of obtaining cross-disciplinary agreement about ends and techniques (Bacheva et al., 2024).

Additionally, transdisciplinary research can be challenging to finance. Many funding agencies prefer narrower projects within one field to discourage experimental collaborations that look beyond this subject matter, such as for climate change or social resilience (Rasulić, 2023). This creates an absence of funds for systematic research programs that could build on the talents of multiple fields.

The second major obstacle is to show real-world effects and impact in a relatively short period of time. Social innovation projects need community involvement and commitment, which are often not simple to gain if the stakeholders are not well informed or the technology does not respond to the community's needs in the short term. Make sure that robotic interventions solve the real-world problem in a humane and socially sustainable way by constantly liaising with many community members and stakeholders.

9.2 Opportunities for Transdisciplinary Approaches

In spite of these hurdles, there is still a tremendous deal of potential for social innovation in transdisciplinary robotics. The integration of the diverse fields of expertise could result in more wholehearted solutions to challenging social problems. For instance, integrating social science in robotic design can make technology easier to use for environmental monitoring to respond to climate change (Bacheva et al., 2024).

It also encourages creativity in the way that transdisciplinarity supports different views and approaches to problems. This variety can then be harnessed to build new robotic systems capable of better performing roles in disaster response, agriculture, and sustainable urban development. Using input from engineers, ecologists, and communities, robotics can adapt to the changing needs of climate adaptation and workforce resilience (Bacheva et al., 2024).

Furthermore, the fact that society's attention now turns toward sustainability and climate adaptation also makes it a fertile ground for funding and assistance. Governments and industry have started to notice

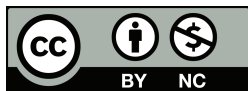
the necessity of investing in technologies that will enable adaptation to climate change, opening up the opportunity for transdisciplinary research (Rasulić, 2023). The cross-disciplinary efforts can draw on this encouragement to design robotic solutions that automate not just the work but are also part of more general sustainability and social justice initiatives.

10 Conclusion

This paper points out that transdisciplinary robotics can be used to promote social innovation as a response to the big challenges we face worldwide, such as climate change and labor migration. Complex problems need a transdisciplinary approach because it brings together expertise from engineering, social sciences, and environmental studies. It can provide breakthrough solutions better than solutions produced separately. Stakeholders and communities must also be involved in achieving robotic solutions. Involving diverse stakeholders allows technologies to be more accurately designed to meet the needs and problems of society in order to produce socially acceptable and effective solutions. Robotics can also play a significant role in sustainability strategies like precision agriculture and waste reduction, which are critical to environmental reduction. These technologies can make communities more resilient by fostering sustainable living and better use of resources. The paper points out also the issues surrounding transdisciplinary methods, including the lack of funding and the difficulties of multidisciplinary cooperation. We need to overcome these barriers if robotics are ever to be applied to social problems. Structured methods and continuous feedback loops are stressed in order for robots to respond to changing community demands and environments. This flexibility is key to how robotics can long-term succeed in fostering social innovation and solving urgent global problems. The conclusion of the paper is that robotics needs to be viewed holistically and collaboratively if we are to resolve the present challenges facing society and ensure a more equal and sustainable future.

Funding: This research received no external funding.

Conflicts of Interest: The author states that there are no known conflicts of interest associated with the publication of this article.



Copyright © 2025 by the authors. This is an open access article distributed under the Creative Commons Attribution License (CC BY-NC International, <https://creativecommons.org/licenses/by/4.0/>), which allow others to share, make adaptations, tweak, and build upon your work non-commercially, provided the original work is properly cited. The authors can reuse their work commercially.

References

- Adebayo, R. A., Obiuto, N. C., Festus-Ikhuoria, I. C., & Olajiga, O. K. (2024). Robotics in Manufacturing: A Review of Advances in Automation and Workforce Implications. *International Journal of Advanced Multidisciplinary Research and Studies*, 4(2), 632–638. <https://doi.org/10.62225/2583049x.2024.4.2.2549>
- Adhikari, P. (2024). Exploring Nexus between Artificial Intelligence job Displacement: A Literature Review. *Journal of National Development*, 37(1), 1–13. <https://doi.org/10.62047/jnd.2024.06.30.1>
- Advanced Robotics for Manufacturing Institute. (2024). *The nation's leading collaborative in robotics and workforce innovation*. ARM Institute. <https://arminstitute.org/> (accessed November 19, 2024)
- Agarwala, C., Jemaneh, J., & Kassie, Y. (2022). Government Policies and Sustainable Food Systems: Navigating Challenges, Seizing Opportunities, and Advancing Environmental and Social Resilience. *Law And Economics*, 16(2), 88–102. <https://doi.org/10.35335/laweco.v16i2.53>

- Alcover, C.-M., Guglielmi, D., Depolo, M., & Mazzetti, G. (2021). "Aging-and-Tech Job Vulnerability": A proposed framework on the dual impact of aging and AI, robotics, and automation among older workers. *Organizational Psychology Review*, 11(2), 175–201. <https://doi.org/10.1177/2041386621992105>
- Aucune, E., Kirchgeorg, S., Valentini, A., Pellissier, L., Deiner, K., & Mintchev, S. (2023). Drone-assisted collection of environmental DNA from tree branches for biodiversity monitoring. *Science Robotics*, 8(74), eadd5762. <https://doi.org/10.1126/scirobotics.add5762>
- Bacheva, V., Madison, I., Baldwin, M., Beilstein, M., Call, D. F., Deaver, J. A., Efimenko, K., Genzer, J., Grieger, K., Gu, A. Z., Ilman, M. M., Liu, J., Li, S., Mayer, B. K., Mishra, A. K., Nino, J. C., Rubambiza, G., Sengers, P., Shepherd, R., . . . Stroock, A. (2024). Transdisciplinary collaborations for advancing sustainable and resilient agricultural systems. arXiv (Cornell University), 1–25. <https://doi.org/10.48550/arxiv.2409.12337>
- Baker, A. (2017). *Zipline Drones and the Lives They Saved*. TIME.com. <https://time.com/rwanda-drones-zipline/> (accessed November 20, 2024)
- Bandile, A. (2024). The Effect of Urbanization on Community Social Networks and Support Systems. *International Journal of Humanity and Social Sciences (IJHSS)*, 3(3), 46–59. <https://doi.org/10.47941/ijhss.2084>
- Blaurock, M., Čaić, M., Okan, M., & Henkel, A. P. (2022). A transdisciplinary review and framework of consumer interactions with embodied social robots: Design, delegate, and deploy. *International Journal of Consumer Studies*, 46(5), 1877–1899. <https://doi.org/10.1111/ijcs.12808>
- Cai, Y., Ferrer, B. R., & Lastra, J. L. M. (2019). Building University-Industry Co-Innovation Networks in Transnational Innovation Ecosystems: Towards a Transdisciplinary Approach of Integrating Social Sciences and Artificial Intelligence. *Sustainability*, 11(17), 1–23. <https://doi.org/10.3390/su11174633>
- Capasso, M. (2023). Responsible Social Robotics and the Dilemma of Control. *International Journal of Social Robotics*, 15, 1981–1991. <https://doi.org/10.1007/s12369-023-01049-2>
- Chen, S. (2023). How roboticists can tackle climate change. IEEE Spectrum. <https://spectrum.ieee.org/robotics-climate-change> (accessed November 20, 2024)
- Chen, S. (2023). How Roboticists Can Tackle Climate Change. *IEEE Spectrum*. Retrieved December 25, 2024, from <https://spectrum.ieee.org/robotics-climate-change>
- Corrales-Paredes, A., Sanz, D. O., Terrón-López, M.-J., & Egidio-García, V. (2023). User Experience Design for Social Robots: A Case Study in Integrating Embodiment. *Sensors*, 23(11), 1–19. <https://doi.org/10.3390/s23115274>
- Darmadi, D., Gardanova, Z. R., Mikhailova, M. V., Al-Qaim, Z. H., Kostyrin, E. V., Kosov, M. E., & Vasiljeva, M. V. (2023). Enhancing Global Health System Resilience and Sustainability Post-COVID-19: A Grounded Theory Approach. *Emerging Science Journal*, 7(6), 2022–2049. <https://doi.org/10.28991/esj-2023-07-06-011>
- Dennison, B. (2017). Transdisciplinary literacy: Seven principles that help define transdisciplinary research. *Integration and Application Network*. Retrieved December 25, 2024, from <https://ian.umces.edu/blog/transdisciplinary-literacy-seven-principles-that-help-define-transdisciplinary-research/>
- Dickson, R. (2023). *How Robots Are Revolutionizing the Fight Against Climate Change in Ways You Never Imagined*. Firgelli Automations. https://www.firgelliauto.com/blogs/news/robots-are-revolutionizing-climate-change?srsId=AfmBOoQ5_BprLEdV4OR_UVnqM4gyRWBA92cqmb8um3bQrgxM6XaFXgb (accessed November 19, 2024)
- Domdouzis, K. (2021). Automated Agricultural Robot and Sensor Data Collection and Analysis through a Biomass Feedstock Production Information System. *International Conference on Robotics and Automation*, 8, 12–18. <https://doi.org/10.15377/2409-9694.2021.08.2>
- Ebbrecht, G., & Chen, J. (2023). Data-Driven Analysis and Optimization for Urban Energy Systems Equitable Resilience. 2023 57th Annual Conference on Information Sciences and Systems (CISS), 1–6. <https://doi.org/10.1109/ciss56502.2023.10089717>
- Etemad-Sajadi, R. (2022). 6 main ethical concerns of service robots and human interaction. *EHL Insights*. <https://hospitalityinsights.ehl.edu/service-robots-and-ethics> (accessed November 19, 2024)

- Gangoda, A., Krasley, S., & Cobb, K. (2023). AI digitalisation and automation of the apparel industry and human workforce skills. *International Journal of Fashion Design Technology and Education*, 16(3), 319–329. <https://doi.org/10.1080/17543266.2023.2209589>
- Gehlert, S., Carothers, B. J., Lee, J. A., Gill, J., Luke, D., & Colditz, G. (2015). A Social Network Analysis Approach to Diagnosing and Improving the Functioning of Transdisciplinary Teams in Public Health. *Transdisciplinary Journal of Engineering & Science*, 6, 11–22. <https://doi.org/10.22545/2015/00070>
- Hansen, G., Benson, J. R., Danish, M. R., Truong, K., Yu, X., & Saniie, J. (2024). Advanced robotic surveillance for urban air quality safety. 2024 *IEEE International Conference on Electro Information Technology (EIT)*, 167–172. <https://doi.org/10.1109/eit60633.2024.10609887>
- Herrera-Vega, E. (2022). Harnessing Ethical AI Surveillance for Climate Change Governmentality. *Transdisciplinary Journal of Engineering & Science*, 13, 129–146. <https://doi.org/10.22545/2022/00205>
- Hess, D. C. (2020). Military Family Readiness: The importance of building familial resilience and increasing family well-being through military community support and services. *Contemporary Military Challenges*, 22(2), 89–99. <https://doi.org/10.33179/bsv.99.svi.11.cmc.22.2.5>
- Hitz, G., Galceran, E., Garneau, M.-E., Pomerleau, F., & Siegwart, R. (2017). Adaptive continuous-space informative path planning for online environmental monitoring. *Journal of Field Robotics*, 34(8), 1427–1449. <https://doi.org/10.1002/rob.21722>
- Höpfl, F., Peisl, T., & Greiner, C. (2023). Exploring stakeholder perspectives: Enhancing robot acceptance for sustainable healthcare solutions. *Sustainable Technology and Entrepreneurship*, 2(3), 1–10. <https://doi.org/10.1016/j.stae.2023.100045>
- Karangutkar, A. A. (2023). The Impact of Artificial Intelligence on Job Displacement and the Future of Work. *International Journal of Advanced Research in Science Communication and Technology (IJARSCT)*, 3(1), 635–638. <https://doi.org/10.48175/ijarsct-12096>
- Khanna, T., & Gonzalez, G. (2020). *Zipline: The World's Largest Drone Delivery Network*. Harvard Business School Case 721-366. <https://www.hbs.edu/faculty/Pages/item.aspx?num=59187> (accessed November 20, 2024)
- Lan, T., Romanello, L., Kovac, M., Armanini, S. F., & Kocer, B. B. (2024). Aerial Tensile Perching and Disentangling Mechanism for Long-Term Environmental Monitoring. 2024 *IEEE International Conference on Robotics and Automation (ICRA)*, 3827–3833. <https://doi.org/10.1109/icra57147.2024.10609975>
- Laut, J., High, B., Nov, O., & Porfiri, M. (2016). A Robotic Vehicle for Aquatic Environmental Monitoring. In *Dynamic Systems and Control Conference* (Vol. 57267, pp. 1-7). American Society of Mechanical Engineers. <https://doi.org/10.1115/dscc2015-9748>
- Lawrence, R. J. (2022). Being Human: Rethinking Adaptation and Resilience. *Transdisciplinary Journal of Engineering & Science*, 13, 147–160. <https://doi.org/10.22545/2022/00208>
- Leiria, A., & Martins, P. (2022). A Transdisciplinary Perspective about Climate Change: A Case of Portugal. *Transdisciplinary Journal of Engineering & Science*, 13, 1–6. <https://doi.org/10.22545/2021/00171>
- Li, L., Serido, J., Vosylis, R., Sorgente, A., Lep, Ž., Zhang, Y., Fonseca, G., Crespo, C., Relvas, A. P., Zupančič, M., & Lanz, M. (2023). Employment Disruption and Wellbeing Among Young Adults: A Cross-National Study of Perceived Impact of the COVID-19 Lockdown. *Journal of Happiness Studies*, 24(3), 991–1012. <https://doi.org/10.1007/s10902-023-00629-3>
- Mahajan, A., Aman, Bhutani, A., & Bhutani, A. (2023). Embracing Automation: Unraveling the Future of Workforce in the United States and the United Kingdom. *International Journal of Science and Research (IJSR)*, 12(9), 689–694. <https://doi.org/10.21275/sr23907100813>
- Mahendran, P. K. R. (2024). The Future of Work – How RPA is Transforming Job Roles and Skill Requirements. *International Journal of Advanced Research in Science Communication and Technology (IJARSCT)*, 4(1), 555–557. <https://doi.org/10.48175/ijarsct-19371>
- Mapue, J. (2024). *16 top companies in the vanguard of the rise of humanoid robots*. Ross Dawson. <https://rossdawson.com/futurist/companies-creating-future/top-companies-rise-humanoid-robots/> (accessed November 20, 2024)

- McManus, I. P. (2023). Workforce automation risks across race and gender in the United States. *American Journal of Economics and Sociology*, 83(2), 463–492. <https://doi.org/10.1111/ajes.12554>
- Michalec, O., O'Donovan, C., & Sobhani, M. (2021). What is robotics made of? The interdisciplinary politics of robotics research. *Humanities and Social Sciences Communications*, 8(1), 1–15. <https://doi.org/10.1057/s41599-021-00737-6>
- Moñivas, J. R. (2022). Limits and Possibilities of Resilience as a Psycho-Sociological Strategic Game: *Transdisciplinary Journal of Engineering & Science*, 13, 1–13. <https://doi.org/10.22545/2022/00191>
- Nambisan, S., Lyytinen, K., & Yoo, Y. (2020). Chapter 1 Digital innovation: towards a transdisciplinary perspective. In *Edward Elgar Publishing eBooks* (pp. 2–12). <https://doi.org/10.4337/9781788119986.00008>
- National Governors Association. (2020). *Reimagining workforce policy in the age of disruption*. National Governors Association. <https://www.nga.org/publications/workforce-policy-in-age-of-disruption/>
- Nkwazema, O. C., Yin, L., & Jannah, M. (2021). Investigation and Application of Robotics and Automation System for Construction Machinery and Environmental Monitoring. *North American Academic Research (NAAR) Journal*, 4(7), 120–130. <https://doi.org/10.5281/zenodo.5148629>
- Nnamdi, N., Ogunlade, B. Z., & Abegunde, B. (2023). An Evaluation of the Impact of Artificial Intelligence on Socio-Economic Human Rights: A Discourse on Automation and Job Loss. *Scholars International Journal of Law, Crime and Justice*, 6(10), 508–521. <https://doi.org/10.36348/sijlcj.2023.v06i10.001>
- Oladele, I., Orelaja, A., & Hameed, A. H. (2024). Artificial intelligence and automation: creating a more resilient United States workforce. *Journal of Scientific Papers Social Development & Security*, 14(4), 91–104. <https://doi.org/10.33445/sds.2024.14.4.7>
- Pasquale, F. (2021). *The New Laws of Robotics*. *Brooklyn Law Notes*. <https://lawnotes.brooklaw.edu/issue/spring-2021/the-new-laws-of-robotics/> (accessed November 19, 2024)
- Paudel, R. (2024). The Impact of Automation and Artificial Intelligence (AI) on Leadership and the Workforce. *Indonesian Journal of Banking and Financial Technology*, 2(2), 109–124. <https://doi.org/10.55927/fintech.v2i2.8904>
- Peruzzini, M., Wognum, N., Bil, C., & Stjepandic, J. (2020). Special issue on ‘transdisciplinary approaches to digital manufacturing for industry 4.0.’ *International Journal of Computer Integrated Manufacturing*, 33(4), 321–324. <https://doi.org/10.1080/0951192x.2020.1752071>
- Pichot, N., Nadarajah, K., Bonan, I., Caverot, G., Coignard, P., Guiet, J. L., & Somat, A. (2021). Stakeholder involvement in the innovation process: An example in medical robotics, the ROBO-K project. *Annals of Robotics and Automation*, 047–050. <https://doi.org/10.17352/ara.000014>
- Pramjeeth, S., Nupen, D. M., & Jagernath, J. (2022). The Efficacy of a face-to-face Student Engagement Programme delivered in an Online Environment: A Case Study of a Private Higher Education. *digiTAL 2022 Conference Proceedings*, 34–47. https://www.researchgate.net/publication/366733432_digiTAL_2022_Conference_Proceedings#fullTextFileContent
- Raj, H., Mishra, A., Kumar, P., Yadav, H., & Vaibhav, V. (2024). The Impact of AI on Job Roles, Workforce and Employment. *Interantional Journal of Scientific Research in Engineering and Management*, 08(05), 1–4. <https://doi.org/10.55041/ijrsrem33782>
- Rasmussen, B., Andersen, P. D., & Kristensen, A. S. (2007). Challenges in transdisciplinary technology foresight: cognition and robotics. *Foresight*, 9(6), 22–35. <https://doi.org/10.1108/14636680710837280>
- Rasulić, L. (2023). Trends, insights, and innovations in European peripheral nerve surgery. *Neurological Research*, 45(9), 874–875. <https://doi.org/10.1080/01616412.2023.2184035>
- Santamaria, G. D. C. (2015). The Value of Transdisciplinary Collaboration in Robotics Education and Research. *Transdisciplinary Journal of Engineering & Science*, 6, 117–132. <https://doi.org/10.22545/2015/00062>
- Santhosh, A., Unnikrishnan, D., Shibu, S., Meenakshi, K. M., & Joseph, G. (2023). AI Impact on Job Automation. *International Journal of Engineering Technology and Management Sciences*, 7(4), 410–425. <https://doi.org/10.46647/ijetms.2023.v07i04.055>
- Seibt, J., Damholdt, M. F., & Vestergaard, C. (2020). Integrative social robotics, value-driven design, and transdisciplinarity. *Interaction Studies Social Behaviour and Communication in Biological and Artificial Systems*, 21(1), 111–144. <https://doi.org/10.1075/is.18061.sei>

Social Sector Network. (2024). 10 Robotics Innovations to Combat Climate Change. *Social Sector Network*. <https://socialsectornetwork.com/10-robotics-innovations-to-combat-climate-change/> (accessed November 19, 2024)

Taylor, K. H., Shoemaker, C. A., Pliakoni, E. D., Gibson, H., & Sanderson, M. (2022). Community garden practices as indicators of social resilience. *XXXI International Horticultural Congress (IHC2022): International Symposium on Urban Horticulture for Sustainable Food*, 1356, 233–240. <https://doi.org/10.17660/actahortic.2022.1356.27>

University of Technology Sydney (UTS). (2023). *Making a social impact*. BBC StoryWorks. <https://www.bbc.com/storyworks/step-into-your-future/social-impact-ai-robotics> (accessed November 20, 2024)

Williams, F., Zoellner, N., & Hovmand, P. S. (2016). Understanding Global Cancer Disparities: The Role of Social Determinants from System Dynamics Perspective. *Transdisciplinary Journal of Engineering & Science*, 7, 1–13. <https://doi.org/10.22545/2016/00072>

Worcester Polytechnic Institute. (n.d.). *Companies*. Environmental Robotics. <https://www.environmental-robotics.com/companies/> (accessed November 20, 2024)

Disclaimer/Publisher’s Note: The statements, opinions, and data contained in all publications are solely those of the individual author(s) and contributor(s) and not of ATLAS/TJES and/or the editor(s). MDPI and/or the editor(s) disclaim responsibility for any injury to people or property resulting from any ideas, methods, instructions, or products referred to in the content.